# Incremental Learning of Auto-Association Multilayer Perceptrons Network 

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#### Abstract

This paper introduces a new algorithm to reduce the time of updating the weights of auto-association multilayer perceptrons network. The basic idea is to modify the singular value decomposition which has been used in the batch algorithm to update the weights whenever a new row is added to the input matrix. The computation analysis and the experiments show that the new algorithm speeds up the implementation about 5-8 times.


Keywords: Neural networks, auto-association multilayer perceptrons, singular value decomposition.
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## 1. Introduction

Neural Networks (NN) adapt to changing environments and afford the possibility of relatively easy hardware implementation. They can even overcome the drawbacks of classical algorithms or enhance the performance of the classification [5]. The Multilayer Perceptrons (MLP) and the AutoAssociation Multilayer Perceptrons (AAMLP) respectively embed supervised and unsupervised mappings of the input space in their hidden layers. An NN implementation of Sammon's mapping which has been suggested by Mao and Jain, and Kohonen's SelfOrganizing Map (SOM) are other examples of neural networks $[1,6,9]$.

AAMLP is used to provide pattern completion to produce a pattern whenever a portion of it or a distorted pattern is presented. In the second case, the network actually stores pairs of patterns building an association between two sets of patterns. AAMLP is forced to perform an identity mapping through a small hidden layer; in other words the target output pattern is identical to the input pattern. Hence, an AAMLP has a configuration of $M: P: M$ with $M$ units in both the input and output layers and $P<M$ hidden units in the hidden layer [3].

The remainder of this paper is organized as follows. Section 2 presents the basic equations of autoassociation multilayer perceptrons. Section 3 introduces the AAMLP Batch Algorithm. Section 4 updates the components of the singular value decomposition. In section 5 we introduce a new algorithm to update the weights whenever a new row in the input matrix is added. Section 6 discusses the improvement of using the suggested algorithm numerically and analytically.

## 2. Auto-Association Multilayer Perceptrons

The AAMLP consists of an input layer with $M$ input units, a hidden layer with $P$ units and $M$ output unites. Let $X$ be an $M \times N$ real input matrix formed by $N$ input vectors and let $H$ and $Y$ be the $P \times N$ and $M \times N$ matrices formed by the hidden and the output vectors respectively. Subsequently the output matrix $Y$ of the AAMLP is obtained as the result of the following operations:

$$
\begin{align*}
& B=W_{1} X+w_{1} u^{t}  \tag{1}\\
& H=F(B)  \tag{2}\\
& Y=W_{2} H+w_{2} u^{t} \tag{3}
\end{align*}
$$

Where $W_{I}$ is the input-to-hidden $P \times M$ weight matrix, $W_{2}$ is the hidden-to-output $M \times P$ weight matrix, $w_{l}$ and $w_{2}$ are P -vectors of biases and $u$ is N -vector of ones. AAMLP training problem is to find optimal weight matrices $W_{1}, W_{2}$ and bias vectors $w_{l}, w_{2}$ minimizing the mean square error:

$$
J=\|X-Y\|^{2}
$$

Where ||.|| is Euclidean matrix norm. This problem can be solved by the usual Error Back-Propagation (EBP) algorithm as described by Rumelhart et al. [1]. However Bourlard and Kamp propose a new fast algorithm based on standard linear algebra and the Singular Value Decomposition (SVD). Moreover, they show that the nonlinear functions at the hidden layer completely unnecessary [3, 4]. Therefore; we will restrict our study on the linear function $F(B)=B$.

## 3. AAMLP Batch Algorithm

Bourlard and Kamp derive a new algorithm using the SVD. The following discussion summarizes their work [3]:

- Using (3) the mean square error can be rewritten as:

$$
\begin{equation*}
J=\left\|X-W_{2} H+w_{2} u^{t}\right\|^{2} \tag{4}
\end{equation*}
$$

- Minimization of J with respect to $w_{2}$ yields

$$
\begin{equation*}
w_{2}=\left(X-W_{2} H\right) u / N \tag{5}
\end{equation*}
$$

- Substituting (5) in (4) we get:

$$
J=\left\|X\left(I-u u^{t} / N\right)-W_{2} H\left(I-u u^{t} / N\right)\right\|^{2}
$$

Let $X^{\prime}=X\left(I-u u^{t} / N\right)$ and $H^{\prime}=H\left(I-u u^{t} / N\right)$, then

$$
J=\left\|X^{\prime}-W_{2} H^{\prime}\right\|^{2}
$$

$J$ can be minimized if we found the best rank $P$ approximation of $X^{\prime}$, this is a standard problem can be solved by SVD as follows:

$$
\begin{equation*}
S V D\left(X^{\prime}\right)=U_{p} \sum_{p} V_{p}^{t} \tag{6}
\end{equation*}
$$

Where $U_{p}$ and $V_{p}$ are $M \times P$ matrix associated with the eigenvectors of $X^{\prime} X^{\prime}{ }^{t}$ and $X^{\prime}{ }^{t} X^{\prime}$ respectively, and $\sum_{p}$ is a diagonal matrix formed by the roots of the largest $P$ eigenvalues, for more information see [8]. Thus:

$$
W_{2} H^{\prime}=U_{p} \sum_{p} V_{p}^{t}
$$

this implies to:

$$
\begin{equation*}
W_{2}=U_{p} T^{-1} \tag{7}
\end{equation*}
$$

and

$$
H^{\prime}=T \sum_{p} V_{p}^{t}
$$

Where $T$ is an arbitrary non singular $P \times P$ matrix (to reduce the calculations we will use sparse or diagonal matrix), Since $B=H$ then we have

$$
T \sum_{p} V_{p}^{t}=W_{l} X^{\prime}+w_{l} u^{t}\left(I-u u^{t} / N\right)
$$

But $u^{t} u=N$, therefore $\mathrm{w}_{1}$ is arbitrary and

$$
T \sum_{p} V_{p}^{t}=W_{l} X^{\prime}
$$

This implies to

$$
\begin{equation*}
W_{l}=T U_{p}^{t} \tag{8}
\end{equation*}
$$

Finally by replacing H and $W_{2}$ in (3) we get

$$
\begin{equation*}
w_{2}=\left(I-U_{p} U_{p}^{t}\right) X u / N-U_{p} T^{l} w_{1} \tag{9}
\end{equation*}
$$

## Algorithm 1. AAMLP Batch Algorithm

Input: The number of input units $M$, the number of input vectors $N$, the number of the hidden units $P$, The input matrix $X$, an arbitrary non singular matrix $T$, a unit victor $u$, and an arbitrary vector $w_{1}$.
Ouput: The optimal Weights $W_{1}, W_{2}$, and $w_{2}$.

$$
\begin{aligned}
& \text { 1. } X p=X-\left((X * u) * u^{\prime}\right) / N \\
& \text { 2. }[U, S, V]=\operatorname{svd}(X p)
\end{aligned}
$$

3. $U p=U(:, 1: P)$
4. $W 1=T^{*} U p^{\prime}$
5. $W 2=U p * \operatorname{inv}(T)$
6. $M x=(1 / N) * X^{*} u$
7. $\left.w 2=\left(M x-U p *\left(U p^{\prime} * M x\right)\right)-(W 2 * w 1)\right)$

## 4. Updating the SVD

Let $X$ be an $M \times N$ real matrix, SVD of $X=U \Sigma V$ and let $C$ be a new column, then we can update SVD as follows [2, 7]:

$$
S V D([X C])=U^{\prime \prime} \Sigma^{\prime \prime} V^{\prime \prime t}
$$

But the previous components can be computed as follows:

$$
\begin{aligned}
& U^{\prime \prime}=[U J] U^{\prime} \\
& \Sigma^{\prime \prime}=\Sigma^{\prime} \\
& V^{\prime \prime}=\left[\begin{array}{ll}
V & 0 \\
0 & I
\end{array}\right] V^{\prime}
\end{aligned}
$$

where

$$
\begin{aligned}
& F=C-U^{*} U^{t} * C \\
& J=F /\|F\| \\
& L=U^{t} * C \\
& Q=\left[\begin{array}{cc}
\Sigma & L \\
0 & \|F\|
\end{array}\right] \\
& \operatorname{SVD}(Q)=U^{\prime} \Sigma^{\prime} V^{\prime t}
\end{aligned}
$$

## 5. Updating the Weights of AAMLP Network

Suppose that after we have found the weights of AAMLP network; we like to add a new element at the end of each input vector, this means a new row must be added to the end of the input matrix $X$. hence the previous weights must be updated. Let $U_{p}, \Sigma_{p}$ and $V_{p}$ be the singular value decomposition of the input matrix $X$, and let $R$ be the new row, thus the new input matrix is:

$$
\left[\begin{array}{l}
X \\
R
\end{array}\right]
$$

$$
\text { Let }\left[\begin{array}{c}
X^{\prime} \\
R^{\prime}
\end{array}\right]=\left[\begin{array}{c}
X \\
R
\end{array}\right] *\left(I-u u^{t} / N\right) \text { and } p^{\prime}=p+1 \text { be }
$$

the number of hidden units in the new network, this implies to

$$
\begin{aligned}
& X^{\prime}=X\left(I-u u^{t} / N\right) \\
& R^{\prime}=R\left(I-u u^{t} / N\right)
\end{aligned}
$$

and

$$
S V D\left(\left[\begin{array}{l}
X^{\prime} \\
R^{\prime}
\end{array}\right]\right)=S V D\left(\left[\begin{array}{ll}
X^{\prime} & R^{\prime}
\end{array}\right]^{t}\right)
$$

$$
\begin{aligned}
& =S V D\left(\left[X^{\prime} R^{\prime}\right]\right)^{t} \\
& =\left(U_{p^{\prime}}^{\prime \prime} \Sigma_{p^{\prime}}^{\prime \prime} V_{p^{\prime}}^{\prime \prime t}\right)^{t} \\
& =V_{p^{\prime}}^{\prime \prime} \Sigma_{p^{\prime}}^{\prime \prime} U_{p^{\prime}}^{\prime \prime}
\end{aligned}
$$

But, the first component of $S V D\left(\left[\begin{array}{l}X^{\prime} \\ R^{\prime}\end{array}\right]\right)$ can be computed as follows:

$$
\begin{align*}
V_{p^{\prime}}^{\prime \prime} & =\left[\begin{array}{cc}
V_{p} & 0 \\
0 & I
\end{array}\right] V_{p^{\prime}}^{\prime} \\
& =V_{p^{*}} V_{p}^{\prime}+V^{\prime}(p+1, p+1) \tag{10}
\end{align*}
$$

Where

$$
\begin{align*}
& F=R^{\prime}-U_{p} * U_{p}^{t} * R^{\prime}  \tag{11}\\
& L=U_{p}^{t} * R^{\prime}  \tag{12}\\
& Q=\left[\begin{array}{cc}
\Sigma_{p} & L \\
0 & \|F\|
\end{array}\right] \\
& S V D(Q)=U_{p^{\prime}}^{\prime} \Sigma_{p^{\prime}}^{\prime} V_{p^{\prime}}^{\prime t} \tag{13}
\end{align*}
$$

So the new weights are

$$
\begin{gather*}
W_{1}=T V_{p^{\prime}}^{\prime \prime t}  \tag{14}\\
W_{2}=V_{p^{\prime}}^{\prime \prime} T^{-1}  \tag{15}\\
\left.w_{2}=\left(I-V_{p^{\prime}}^{\prime \prime} V_{p^{\prime}}^{\prime \prime}\right) X u / N\right)-V_{p^{\prime}}^{\prime \prime} T^{-l} w_{l} \tag{16}
\end{gather*}
$$

## Algorithm 2. Increment AAMLP algorithm

Input: The number of input units $M$, the number of input vectors $N$, the number of the hidden units $P=P+1$, the component of the input matrix $X$ $\left(U_{p}, \sum_{p}\right.$, and $\left.V_{p}\right)$, an arbitrary non singular matrix T, a unit victor $u$, an arbitrary vector $w_{l}$, and a new row $R$.
Ouput: The optimal Weights $W_{1}, W_{2}$, and $w_{2}$.

1. $X p=X-\left((X * u) * u^{\prime}\right) / N$;
2. $R p=R-\left((R * u) * u^{\prime}\right) / N$;
3. $F=\operatorname{norm}\left(R p-U p *\left(U p^{\prime} * R p\right)\right)$;
4. $L=U p^{\prime} * R p$;
5. $Z(1: 1,1: P)=0$;
6. $Q=[S L ; Z F]$;
7. [U2, $S 2, V 2]=s v d s(Q)$;
8. $V 3=V p$ * V2 $(1: P, 1: P)+V 2(P+1, P+1)$;
9. $W 1=T^{*} V 3^{\prime}$
10. $W 2=V 3 * \operatorname{inv}(T)$
11. $M x=(1 / N) * X^{*} u$
12. $\left.w 2=\left(M x-V 3 *\left(V 3^{\prime} * M x\right)\right)-(W 2 * w 1)\right)$

In algorithm 2 we have used the sparse matrices procedure $s v d s$ () which is considered much faster than the procedure $s v d$ ().

## 6. Complexity Analysis and Experiments

The complexity of the batch algorithm equals to the total complexity of the equations (6-9), it is clear that: The most expensive equation is (6) which takes $O(M * N * C)$ operations where $C=\min (M, N)$, and since the matrix $T$ can be diagonal or sparse the other equations takes $O\left(M^{*} P\right)$ or $O\left(N^{*} P\right)$ operations. On other hand; the complexity of the new algorithm equals the total complexity of the equations (10-16). Equation (10) is the most expensive equation and takes $O\left(M * P^{2}\right)$ operations, but equation (13) takes $O\left(P^{2}\right)$ operations because $Q$ is bordered diagonal (remember that: To reduce the number of multiplications in the other equations we have to multiply matrix_vector before matrix_matrix). Subsequence the new algorithm is faster than the batch algorithm because $P \leq \min (M$, $N$ ), furthermore; matrices multiplications can be done faster by using Winograd method.

For our experiments, we use random input matrices for training and testing. The machine had 1.2 GH Intel Pentium 4 CPU with 256 MB and the code implemented by using MATLAB 6.5. Table 1 and Figure 1 show the advantage of using the new algorithm over the batch algorithm if a new row is added to the input matrix $X$.

Table 1. Comparison between the Batch algorithm and the new algorithm.

| $\mathbf{M}+\mathbf{1}$ | $\mathbf{N}$ | Batch <br> Algorithm <br> (Seconds) | The New <br> Algorithm <br> (Seconds) | Error <br> $\mathbf{J}=\\|\mathbf{X}-\mathbf{Y}\\|^{\mathbf{2}}$ |
| :---: | :---: | :---: | :---: | :---: |
| 301 | 300 | 3.02 | 0.67 | $0.1^{*} 10^{-10}$ |
| 401 | 450 | 9.04 | 1.21 | $0.1^{*} 10^{-10}$ |
| 501 | 550 | 17.34 | 3.64 | $0.4^{*} 10^{-11}$ |
| 601 | 500 | 30.33 | 6.12 | $0.4^{*} 10^{-11}$ |
| 701 | 700 | 49.50 | 8.5 | $0.3^{*} 10^{-11}$ |
| 801 | 900 | 85.96 | 13.94 | $0.1^{*} 10^{-11}$ |
| 1201 | 1100 | 258.41 | 43.18 | $0.2^{*} 10^{-12}$ |
| 1601 | 1600 | 873.91 | 143.68 | $0.2^{*} 10^{-12}$ |
| 2001 | 2100 | 3665.4 | 513.08 | $0.1^{*} 10^{-12}$ |



Figure 1. Comparison between the batch algorithm and the new algorithm.

## 7. Conclusion

We have shown that the implementation of the new algorithm reduces the time of updating the weights of auto-association multilayer perceptrons whenever a new row is added to the input matrix. The comparison shows that the new algorithm speeds up the computation about 5-8 times. This work can be extended easily if a new input vector (or column) is added to the input matrix.

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